Dual output 4-20 mA sensors

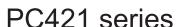




Table 1: PC421xxx-yy-DA dual output model selection guide

, , , , , , , , , , , , , , , , , , ,		3
xxx (4-20 mA output type)	yy (4-20 mA full scale)	DA (dynamic accel output)
AR = acceleration, RMS ^A AP = acceleration, equiv. peak ^{A,B} ATP = acceleration, true peak ^C	05 = 5 g (49 m/sec ²) 10 = 10 g (98 m/sec ²) 20 = 20 g (196 m/sec ²)	
VR = velocity, RMS ^A VP = velocity, equiv. peak ^{A,B}	05 = 0.5 ips (12.8 mm/sec) 10 = 1.0 ips (25.4 mm/sec) 20 = 2.0 ips (50.8 mm/sec) 30 = 3.0 ips (76.2 mm/sec) 50 = 5.0 ips (127 mm/sec)	DA = dynamic acceleration, 100 mV/g (10.2 mV/m/s²)

MODEL PCAZI SN: 114 0 - 0.5 ips

Key features

 Choice of RMS, equivalent peak or true peak output

· Intrinsically safe certified

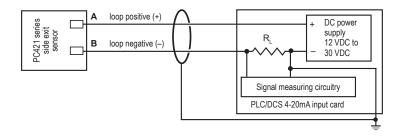
(PC421xx-yy-IS models)

approved ISO 9001 facility

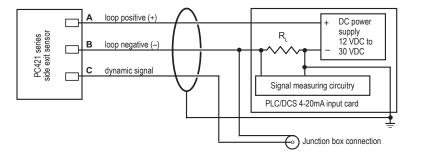
versions available

· Manufactured in an

PC421ATP-yy wiring



PC421xxx-yy-DA wiring



Certifications

ϵ

98893 Rev.E 10/19

Note: Due to continuous process improvement, specifications are subject to change without notice. This document is cleared for public release.

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ARMS and equivalent peak versions (AR, AP, VR, VP) are available only with dynamic acceleration output option. Only PC421ATP models can be purchased without a dynamic output. The PCC421 series, with a 105°C maximum operating temperature, is available for standard (no dynamic output) RMS or equivalent peak models.

^B Equivalent peak output is developed based on the true RMS value of vibration. The equivalent peak output is 1.414 times the RMS value.

^c True peak output is based on the actual measured peak value using the time domain data.

Dual output 4-20 mA sensors

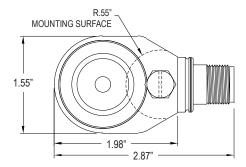


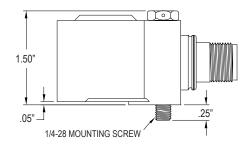
PC421 series

SPECIFICATIONS

Output, 4-20 mA:			
Full scale, 20 mA, ±5%		see Table 1 on p	age 1
Frequency response:	±10% ±3 dB	10 Hz - 1.0 kHz 4.0 Hz - 2.0 kHz	
Repeatability		±2%	
Transverse sensitivity, max		5%	
Output, dynamic (-DA models on	ıly):		
Sensitivity, ±10%		100 mV/g	
Full scale		20 g, peak	
Frequency response, ±3 dB		2.5 Hz - 10 kHz	
Amplitude nonlinearity, max		1%	
Resonant frequency, mounted	d, nom.	21 kHz	
Transverse sensitivity, max		5%	
Power requirements, 2-wire loop Voltage, between pins A and E		12 - 30 VDC	
Loop resistance ¹ at 24 VDC, max		700 Ω	
Turn on time, 4-20 mA loop		30 seconds	
Grounding		case isolated, in	ternally shielded
Temperature range		–40° to +85°C	
Vibration limit		250 g peak	
Shock limit		2,500 g peak	
Sealing		hermetic	
Sensing element design		PZT, shear	
Weight		320 grams	
Case material		316L stainless steel	
Mounting		1/4-28 captive bolt	
		PC421ATP-yy	PC421xxx-yy-DA
Output connector (MIL-C-5015 st	tyle)	2 pin	3 pin
Mating connector		R6 type	R6G type
Recommended cabling		J9T2A	J9T3A
		••••••	

Connections				
Function	Connector pin			
	PC421ATP-yy	-DA models		
loop positive (+)	А	Α		
loop negative (–)	В	В		
dynamic signal	N/A	С		
ground	shell	shell		





Accessories supplied: 1/4-28 captive bolt; calibration data (level 2)

DC supply voltage	R _L (max resistance) ²	R _∟ (minimum wattage capability)³
12 VDC	100 Ω	1/8 watt
20 VDC	500 Ω	1/4 watt
24 VDC	700 Ω	1/2 watt
26 VDC	800 Ω	1/2 watt
30 VDC	1.000 Ω	1/2 watt

Notes: ¹ Maximum loop resistance (R₁) can be calculated by:

$$R_{L} = \frac{V_{DC power} - 10 \text{ V}}{20 \text{ mA}}$$

- 2 Lower resistance is allowed, greater than 10 Ω recommended.
- 3 Minimum R_i wattage determined by: (0.0004 x R_i).

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