



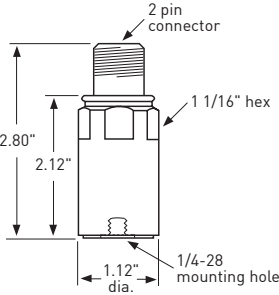
**Features**

- Peak velocity output
- Corrosion resistant
- Hermetic seal
- ESD protection
- Overload protection
- Reverse wiring protection

**Benefits**

- Provides velocity vibration trending
- Provides continuous trending of overall machine vibration
- Can help guide maintenance
- Helps notify of impending equipment failure
- Much-narrower bandwidth response makes 4-20mA output dependent on key fundamental frequencies

The PC420VP-10-B3041 4-20 mA loop powered transducers offer users the ability to monitor vibration at their running speed while ignoring many higher frequency effects. In equipment such as gearboxes there can be high-amplitude vibration at frequencies far above the running speed. This sensor will filter out the higher frequencies and allow users to trend only the low-frequency components such as running speed for machines operating in the 300 RPM to 1500 RPM range.



# Model PC420VP-10-B3041

## Frequency-banded velocity loop powered sensors (LPS™)

**Output, 4-20 mA**

Full scale, 20 mA (±5%) .....	1.0 inches/second
±10% frequency response .....	6Hz - 20Hz
±3 dB .....	3Hz - 40kHz
Repeatability .....	±2%
Transverse sensitivity, max.....	5%

**Electrical**

Power requirements (two wire loop power):

Voltage at PC420 Series sensor terminals.....	10 VDC min, 30 VDC max
Loop resistance <sup>1</sup> at 24 VDC, maximum.....	700Ω
Turn on time, 4-20 mA loop.....	< 45 seconds
Grounding.....	case isolated, internally shielded

**Environmental**

Temperature range .....	-40 to 85°C
Vibration limit .....	250 g peak
Shock limit .....	2,500 g peak
Sealing .....	hermetic

**Physical**

Sensing element design .....	PZT ceramic / shear
Weight .....	162 grams
Case material .....	316L stainless steel
Mounting .....	1/4 - 28 tapped hole
Output connector.....	2 pin, MIL-C-5015 style
Mating connector.....	R6G type
Recommended cabling.....	J9T2A

Connector pin	Function
Shell	ground
A	loop positive (+)
B	loop negative (-)

Accessories supplied: SF6 mounting stud (International customers specify mounting requirements); calibration data (level 2)

**See back for notes and powering diagram.**

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Notes: <sup>1</sup> Maximum loop resistance ( $R_L$ ) can be calculated by:

$$R_L \text{ (max resistance)} = \frac{V_{\text{DC power}} - 10 \text{ V}}{20 \text{ mA}}$$

DC supply voltage	$R_L$ (max resistance) <sup>2</sup>	$R_L$ (minimum wattage capability) <sup>3</sup>
12 VDC	100Ω	1/8 watt
20 VDC	500Ω	1/4 watt
24 VDC	700Ω	1/2 watt
26 VDC	800Ω	1/2 watt
30 VDC	1.0kΩ	1/2 watt

<sup>2</sup> Lower resistance is allowed, greater than 10Ω recommended.

<sup>3</sup> Minimum  $R_L$  wattage determined by:  $(0.0004 \times R_L)$ .

Typical circuit

